

Package ‘EmiR’

July 21, 2025

Type Package

Title Evolutionary Minimizer for R

Version 1.0.5

Author Davide Pagano [aut],
Lorenzo Sostero [aut, cre]

Maintainer Lorenzo Sostero <l.sostero@studenti.unibs.it>

Description A C++ implementation of the following evolutionary algorithms: Bat Algorithm (Yang, 2010 <[doi:10.1007/978-3-642-12538-6_6](https://doi.org/10.1007/978-3-642-12538-6_6)>), Cuckoo Search (Yang, 2009 <[doi:10.1109/nabic.2009.5393690](https://doi.org/10.1109/nabic.2009.5393690)>), Genetic Algorithms (Holland, 1992, ISBN:978-0262581110), Gravitational Search Algorithm (Rashedi et al., 2009 <[doi:10.1016/j.ins.2009.03.004](https://doi.org/10.1016/j.ins.2009.03.004)>), Grey Wolf Optimization (Mirjalili et al., 2014 <[doi:10.1016/j.advengsoft.2013.12.007](https://doi.org/10.1016/j.advengsoft.2013.12.007)>), Harmony Search (Geem et al., 2001 <[doi:10.1177/003754970107600201](https://doi.org/10.1177/003754970107600201)>), Improved Harmony Search (Mahdavi et al., 2007 <[doi:10.1016/j.amc.2006.11.033](https://doi.org/10.1016/j.amc.2006.11.033)>), Moth-flame Optimization (Mirjalili, 2015 <[doi:10.1016/j.knosys.2015.07.006](https://doi.org/10.1016/j.knosys.2015.07.006)>), Particle Swarm Optimization (Kennedy et al., 2001 ISBN:1558605959), Simulated Annealing (Kirkpatrick et al., 1983 <[doi:10.1126/science.220.4598.671](https://doi.org/10.1126/science.220.4598.671)>), Whale Optimization Algorithm (Mirjalili and Lewis, 2016 <[doi:10.1016/j.advengsoft.2016.01.008](https://doi.org/10.1016/j.advengsoft.2016.01.008)>). 'EmiR' can be used not only for unconstrained optimization problems, but also in presence of inequality constrains, and variables restricted to be integers.

License GPL-3

Encoding UTF-8

LazyData true

Depends R (>= 3.5.0)

Imports Rcpp (>= 1.0.5), methods, Rdpack, tictoc, ggplot2, tibble, tidy, dplyr, ganimate, mathjaxr, data.table, graphics

LinkingTo Rcpp, RcppProgress, testthat

RoxygenNote 7.1.2

RdMacros Rdpack, mathjaxr

Suggests xml2, testthat

NeedsCompilation yes

Repository CRAN

Date/Publication 2025-05-13 18:40:02 UTC

Contents

ackley_func	3
animate_population	3
bohachevsky_func	4
config_abc	5
config_algo	6
config_bat	7
config_cs	8
config_ga	9
config_gsa	11
config_gwo	12
config_hs	13
config_ihs	14
config_mfo	15
config_ps	16
config_sa	18
config_woa	19
constrained_function	20
constraint	21
freudenstein_roth_func	21
G01InitPop	22
get_population	22
griewank_func	23
list_of_algorithms	23
list_of_functions	24
miele_cantrell_func	24
minimize	25
MinimizerOpts	26
OptimizationResults	27
parameter	28
parameters	28
plot_history	29
plot_population	29
rastrigin_func	30
rosenbrock_func	30
schwefel_func	31
styblinski_tang_func	32

Index

33

`ackley_func`*Ackley Function*

Description

Implementation of n-dimensional Ackley function, with $a = 20$, $b = 0.2$ and $c = 2\pi$ (see definition below).

Usage`ackley_func(x)`**Arguments**

`x` numeric or complex vector.

Details

On an n-dimensional domain it is defined by

$$f(\vec{x}) = -a \exp\left(-b \sqrt{\frac{1}{n} \sum_{i=1}^n x_i^2}\right) - \exp\left(\frac{1}{n} \sum_{i=1}^n \cos(cx_i)\right) + a + \exp(1),$$

and is usually evaluated on $x_i \in [-32.768, 32.768]$, for all $i = 1, \dots, n$. The function has one global minimum at $f(\vec{x}) = 0$ for $x_i = 0$ for all $i = 1, \dots, n$.

Value

The value of the function.

References

Ackley DH (1987). *A Connectionist Machine for Genetic Hillclimbing*. Springer US. doi:10.1007/9781461319979.

`animate_population`*Animation of population motion*

Description

Create an animation of the population motion for the minimization of 1D and 2D functions. The animation can be produced only if `save_pop_history` is TRUE in the options of the minimizer (see [MinimizerOpts](#)).

Usage

```
animate_population(minimizer_result, n_points = 100)
```

Arguments

`minimizer_result` an object of class `OptimizationResults` (see [OptimizationResults](#)).

`n_points` number of points per dimension used to draw the objective function. Default is 100.

bohachevsky_func	<i>Bohachevsky Function</i>
------------------	-----------------------------

Description

Implementation of 2-dimensional Bohachevsky function.

Usage

```
bohachevsky_func(x)
```

Arguments

`x` numeric or complex vector.

Details

On an 2-dimensional domain it is defined by

$$f(\vec{x}) = x_1^2 + 2x_2^2 - 0.3 \cos(3\pi x_1) - 0.4 \cos(4\pi x_2) + 0.7$$

and is usually evaluated on $x_i \in [-100, 100]$, for all $i = 1, 2$. The function has one global minimum at $f(\vec{x}) = 0$ for $\vec{x} = [0, 0]$.

Value

The value of the function.

References

Bohachevsky IO, Johnson ME, Stein ML (1986). “Generalized simulated annealing for function optimization.” *Technometrics*, **28**(3), 209–217.

`config_abc`*Configuration object for the Artificial Bee Colony Algorithm*

Description

Create a configuration object for the Artificial Bee Colony Algorithm (ABC). At minimum the number of iterations (parameter `iterations`) and the number of bees (parameter `population_size`) have to be provided.

Usage

```
config_abc(  
    iterations,  
    population_size,  
    iterations_same_cost = NULL,  
    absolute_tol = NULL,  
    employed_frac = 0.5,  
    n_scout = 1  
)
```

Arguments

<code>iterations</code>	maximum number of iterations.
<code>population_size</code>	number of bees.
<code>iterations_same_cost</code>	maximum number of consecutive iterations with the <i>same</i> (see the parameter <code>absolute_tol</code>) best cost before ending the minimization. If NULL the minimization continues for the number of iterations specified by the parameter <code>iterations</code> . Default is NULL.
<code>absolute_tol</code>	absolute tolerance when comparing best costs from consecutive iterations. If NULL the machine epsilon is used. Default is NULL.
<code>employed_frac</code>	fraction employed bees. Default is 0.5.
<code>n_scout</code>	number of scout bees. Default is 1.

Value

`config_abc` returns an object of class `ABCCConfig`.

References

Karaboga D, Basturk B (2007). "A powerful and efficient algorithm for numerical function optimization: artificial bee colony (ABC) algorithm." *Journal of Global Optimization*, **39**(3), 459–471. [doi:10.1007/s108980079149x](https://doi.org/10.1007/s108980079149x).

Examples

```
conf <- config_abc(iterations = 100, population_size = 50, iterations_same_cost = NULL,
absolute_tol = NULL, employed_frac = 0.5, n_scout = 1)
```

config_algo

Configuration object for algorithms

Description

Create a configuration object for one of the algorithms available in EmiR. At minimum the id of the algorithm (parameter `algorithm_id`), the number of iterations (parameter `iterations`) and the number of individuals in the population (parameter `population_size`) have to be provided.

Usage

```
config_algo(
  algorithm_id,
  iterations,
  population_size,
  iterations_same_cost = NULL,
  absolute_tol = NULL,
  ...
)
```

Arguments

<code>algorithm_id</code>	id of the algorithm to be used. See list_of_algorithms for the list of the available algorithms.
<code>iterations</code>	maximum number of iterations.
<code>population_size</code>	number of individuals in the population.
<code>iterations_same_cost</code>	maximum number of consecutive iterations with the <i>same</i> (see the parameter <code>absolute_tol</code>) best cost before ending the minimization. If <code>NULL</code> the minimization continues for the number of iterations specified by the parameter <code>iterations</code> . Default is <code>NULL</code> .
<code>absolute_tol</code>	absolute tolerance when comparing best costs from consecutive iterations. If <code>NULL</code> the machine epsilon is used. Default is <code>NULL</code> .
<code>...</code>	algorithm specific parameters (see specific configuration functions for more details).

Value

`config_algo` returns a configuration object specific for the specified algorithm.

Examples

```
conf <- config_algo(algorithm_id = "PS", population_size = 200, iterations = 10000)
```

config_bat

*Configuration object for the Bat Algorithm***Description**

Create a configuration object for the Bat Algorithm (BAT). At minimum the number of iterations (parameter `iterations`) and the number of bats (parameter `population_size`) have to be provided.

Usage

```
config_bat(
  iterations,
  population_size,
  iterations_same_cost = NULL,
  absolute_tol = NULL,
  initial_loudness = 1.5,
  alpha = 0.9,
  initial_pulse_rate = 0.5,
  gamma = 0.9,
  freq_min = 0,
  freq_max = 2
)
```

Arguments

<code>iterations</code>	maximum number of iterations.
<code>population_size</code>	number of bats.
<code>iterations_same_cost</code>	maximum number of consecutive iterations with the <i>same</i> (see the parameter <code>absolute_tol</code>) best cost before ending the minimization. If <code>NULL</code> the minimization continues for the number of iterations specified by the parameter <code>iterations</code> . Default is <code>NULL</code> .
<code>absolute_tol</code>	absolute tolerance when comparing best costs from consecutive iterations. If <code>NULL</code> the machine epsilon is used. Default is <code>NULL</code> .
<code>initial_loudness</code>	initial loudness of emitted pulses. Typical values are in the range $[1, 2]$. Default is <code>1.5</code> .
<code>alpha</code>	parameter to control the linearly decreasing loudness with the iterations. It should be between <code>0</code> and <code>1</code> . Default is <code>0.9</code> .

initial_pulse_rate	initial rate at which pulses are emitted. It should be between 0 and 1. Default is 0.5.
gamma	parameter to control the exponentially decreasing pulse rate with the iterations. Default is 0.9.
freq_min	minimum frequency value of pulses. Default is 0.
freq_max	maximum frequency value of pulses. Default is 2.0.

Value

config_bat returns an object of class BATConfig.

References

Yang X (2010). "A new metaheuristic bat-inspired algorithm." In *Nature inspired cooperative strategies for optimization (NICSO 2010)*, 65–74. Springer.

Examples

```
conf <- config_bat(iterations = 100, population_size = 50, iterations_same_cost = NULL,
absolute_tol = NULL, initial_loudness = 1.5, alpha = 0.9,
initial_pulse_rate = 0.5, gamma = 0.9,
freq_min = 0., freq_max = 2.)
```

config_cs

Configuration object for the Cuckoo Search Algorithm

Description

Create a configuration object for the Cuckoo Search Algorithm (CS). At minimum the number of iterations (parameter iterations) and the number of host nests (parameter population_size) have to be provided.

Usage

```
config_cs(
  iterations,
  population_size,
  iterations_same_cost = NULL,
  absolute_tol = NULL,
  discovery_rate = 0.25,
  step_size = 1
)
```


Arguments

iterations	maximum number of iterations.
population_size	number of host nests.
iterations_same_cost	maximum number of consecutive iterations with the <i>same</i> (see the parameter <code>absolute_tol</code>) best cost before ending the minimization. If NULL the minimization continues for the number of iterations specified by the parameter <code>iterations</code> . Default is NULL.
absolute_tol	absolute tolerance when comparing best costs from consecutive iterations. If NULL the machine epsilon is used. Default is NULL.
discovery_rate	probability for the egg laid by a cuckoo to be discovered by the host bird. It should be between 0 and 1. Default is 0.25.
step_size	step size of the Levy flight. Default is 1.0.

Value

`config_cs` returns an object of class `CSConfig`.

References

Yang X, Deb S (2009). "Cuckoo Search via Lévy flights." In *2009 World Congress on Nature & Biologically Inspired Computing (NaBIC)*. doi:10.1109/nabic.2009.5393690.

Examples

```
conf <- config_cs(iterations = 100, population_size = 50, iterations_same_cost = NULL,
absolute_tol = NULL, discovery_rate = 0.25, step_size = 1.0)
```

config_ga

Configuration object for the Genetic Algorithm

Description

Create a configuration object for the Genetic Algorithm (GA). At minimum the number of iterations (parameter `iterations`) and the number of chromosomes (parameter `population_size`) have to be provided.

Usage

```
config_ga(  
  iterations,  
  population_size,  
  iterations_same_cost = NULL,  
  absolute_tol = NULL,  
  keep_fraction = 0.4,  
  mutation_rate = 0.1  
)
```

Arguments

iterations	maximum number of iterations.
population_size	number of chromosomes.
iterations_same_cost	maximum number of consecutive iterations with the <i>same</i> (see the parameter <code>absolute_tol</code>) best cost before ending the minimization. If <code>NULL</code> the minimization continues for the number of iterations specified by the parameter <code>iterations</code> . Default is <code>NULL</code> .
absolute_tol	absolute tolerance when comparing best costs from consecutive iterations. If <code>NULL</code> the machine epsilon is used. Default is <code>NULL</code> .
keep_fraction	fraction of the population that survives for the next step of mating. Default is 0.4.
mutation_rate	probability of mutation. Default is 0.1.

Value

`config_ga` returns an object of class `GAConfig`.

References

Holland JH (1992). *Adaptation in Natural and Artificial Systems: An Introductory Analysis with Applications to Biology, Control and Artificial Intelligence*. MIT Press, Cambridge, MA, USA. ISBN 0262082136.

Examples

```
conf <- config_ga(iterations = 100, population_size = 50, iterations_same_cost = NULL,  
  absolute_tol = NULL, keep_fraction = 0.4, mutation_rate = 0.1)
```

`config_gsa`*Configuration object for the Gravitational Search Algorithm*

Description

Create a configuration object for the Gravitational Search Algorithm (GSA). At minimum the number of iterations (parameter `iterations`) and the number of planets (parameter `population_size`) have to be provided.

Usage

```
config_gsa(  
    iterations,  
    population_size,  
    iterations_same_cost = NULL,  
    absolute_tol = NULL,  
    grav = 1000,  
    grav_evolution = 20  
)
```

Arguments

<code>iterations</code>	maximum number of iterations.
<code>population_size</code>	number of planets.
<code>iterations_same_cost</code>	maximum number of consecutive iterations with the <i>same</i> (see the parameter <code>absolute_tol</code>) best cost before ending the minimization. If NULL the minimization continues for the number of iterations specified by the parameter <code>iterations</code> . Default is NULL.
<code>absolute_tol</code>	absolute tolerance when comparing best costs from consecutive iterations. If NULL the machine epsilon is used. Default is NULL.
<code>grav</code>	gravitational constant, involved in the acceleration of planets. Default is 100.
<code>grav_evolution</code>	parameter to control the exponentially decreasing gravitational constant with the iterations. Default is 20.0.

Value

`config_gsa` returns an object of class `GSACConfig`.

References

Rashedi E, Nezamabadi-pour H, Saryazdi S (2009). "GSA: A Gravitational Search Algorithm." *Information Sciences*, **179**(13), 2232–2248. doi:10.1016/j.ins.2009.03.004.

Examples

```
conf <- config_gsa(iterations = 100, population_size = 50, iterations_same_cost = NULL,
absolute_tol = NULL, grav = 1000, grav_evolution = 20.)
```

config_gwo

Configuration object for the Grey Wolf Optimizer Algorithm

Description

Create a configuration object for the Grey Wolf Optimizer Algorithm (GWO). At minimum the number of iterations (parameter `iterations`) and the number of wolves (parameter `population_size`) have to be provided.

Usage

```
config_gwo(
  iterations,
  population_size,
  iterations_same_cost = NULL,
  absolute_tol = NULL
)
```

Arguments

<code>iterations</code>	maximum number of iterations.
<code>population_size</code>	number of wolves.
<code>iterations_same_cost</code>	maximum number of consecutive iterations with the <i>same</i> (see the parameter <code>absolute_tol</code>) best cost before ending the minimization. If <code>NULL</code> the minimization continues for the number of iterations specified by the parameter <code>iterations</code> . Default is <code>NULL</code> .
<code>absolute_tol</code>	absolute tolerance when comparing best costs from consecutive iterations. If <code>NULL</code> the machine epsilon is used. Default is <code>NULL</code> .

Value

`config_gwo` returns an object of class `GWConfig`.

References

Mirjalili S, Mirjalili SM, Lewis A (2014). “Grey Wolf Optimizer.” *Advances in Engineering Software*, **69**, 46–61. doi:10.1016/j.advengsoft.2013.12.007.

Examples

```
conf <- config_gwo(iterations = 100, population_size = 50, iterations_same_cost = NULL,
  absolute_tol = NULL)
```

 config_hs

Configuration object for the Harmony Search Algorithm

Description

Create a configuration object for the Harmony Search Algorithm (HS). At minimum the number of iterations (parameter `iterations`) and the number of solutions in the harmony memory (parameter `population_size`) have to be provided.

Usage

```
config_hs(
  iterations,
  population_size,
  iterations_same_cost = NULL,
  absolute_tol = NULL,
  considering_rate = 0.5,
  adjusting_rate = 0.5,
  distance_bandwidth = 0.1
)
```

Arguments

<code>iterations</code>	maximum number of iterations.
<code>population_size</code>	number of solutions in the harmony memory.
<code>iterations_same_cost</code>	maximum number of consecutive iterations with the <i>same</i> (see the parameter <code>absolute_tol</code>) best cost before ending the minimization. If <code>NULL</code> the minimization continues for the number of iterations specified by the parameter <code>iterations</code> . Default is <code>NULL</code> .
<code>absolute_tol</code>	absolute tolerance when comparing best costs from consecutive iterations. If <code>NULL</code> the machine epsilon is used. Default is <code>NULL</code> .
<code>considering_rate</code>	probability for each component of a newly generated solution to be recalled from the harmony memory.
<code>adjusting_rate</code>	probability of the pitch adjustment in case of a component recalled from the harmony memory.
<code>distance_bandwidth</code>	amplitude of the random pitch adjustment.

Value

config_hs returns an object of class HSConfig.

References

Lee KS, Geem ZW (2004). "A new structural optimization method based on the harmony search algorithm." *Computers & Structures*, **82**(9-10), 781–798. doi:10.1016/j.compstruc.2004.01.002.

Examples

```
conf <- config_hs(iterations = 100, population_size = 50, iterations_same_cost = NULL,
absolute_tol = NULL, considering_rate = 0.5, adjusting_rate = 0.5,
distance_bandwidth = 0.1)
```

config_ihs

Configuration object for the Improved Harmony Search Algorithm

Description

Create a configuration object for the Improved Harmony Search Algorithm (IHS). At minimum the number of iterations (parameter `iterations`) and the number of solutions in the harmony memory (parameter `population_size`) have to be provided.

Usage

```
config_ihs(
  iterations,
  population_size,
  iterations_same_cost = NULL,
  absolute_tol = NULL,
  considering_rate = 0.5,
  min_adjusting_rate = 0.3,
  max_adjusting_rate = 0.99,
  min_distance_bandwidth = 1e-04,
  max_distance_bandwidth = 1
)
```

Arguments

`iterations` maximum number of iterations.
`population_size` number of solutions in the harmony memory.

iterations_same_cost	maximum number of consecutive iterations with the <i>same</i> (see the parameter <code>absolute_tol</code>) best cost before ending the minimization. If NULL the minimization continues for the number of iterations specified by the parameter <code>iterations</code> . Default is NULL.
absolute_tol	absolute tolerance when comparing best costs from consecutive iterations. If NULL the machine epsilon is used. Default is NULL.
considering_rate	probability for each component of a newly generated solution to be recalled from the harmony memory.
min_adjusting_rate	minimum value of the pitch adjustment probability.
max_adjusting_rate	maximum value of the pitch adjustment probability.
min_distance_bandwidth	minimum amplitude of the random pitch adjustment.
max_distance_bandwidth	maximum amplitude of the random pitch adjustment.

Value

`config_ihs` returns an object of class `IHSConfig`.

References

Mahdavi M, Fesanghary M, Damangir E (2007). “An improved harmony search algorithm for solving optimization problems.” *Applied Mathematics and Computation*, **188**(2), 1567–1579. doi:10.1016/j.amc.2006.11.033.

Examples

```
conf <- config_ihs(iterations = 100, population_size = 50, iterations_same_cost = NULL,
absolute_tol = NULL, considering_rate = 0.5, min_adjusting_rate = 0.3,
max_adjusting_rate = 0.99, min_distance_bandwidth = 0.0001, max_distance_bandwidth = 1)
```

code config_mfo

Configuration object for the Moth-flame Optimization Algorithm

Description

Create a configuration object for the Moth-flame Optimization Algorithm (MFO). At minimum the number of iterations (parameter `iterations`) and the number of moths (parameter `population_size`) have to be provided.

Usage

```
config_mfo(  
  iterations,  
  population_size,  
  iterations_same_cost = NULL,  
  absolute_tol = NULL  
)
```

Arguments

<code>iterations</code>	maximum number of iterations.
<code>population_size</code>	number of moths.
<code>iterations_same_cost</code>	maximum number of consecutive iterations with the <i>same</i> (see the parameter <code>absolute_tol</code>) best cost before ending the minimization. If NULL the minimization continues for the number of iterations specified by the parameter <code>iterations</code> . Default is NULL.
<code>absolute_tol</code>	absolute tolerance when comparing best costs from consecutive iterations. If NULL the machine epsilon is used. Default is NULL.

Value

`config_mfo` returns an object of class `MFOConfig`.

References

Mirjalili S (2015). “Moth-flame optimization algorithm: A novel nature-inspired heuristic paradigm.” *Knowledge-Based Systems*, **89**, 228–249. doi:10.1016/j.knosys.2015.07.006.

Examples

```
conf <- config_mfo(iterations = 100, population_size = 50, iterations_same_cost = NULL,  
absolute_tol = NULL)
```

config_ps

Configuration object for the Particle Swarm Algorithm

Description

Create a configuration object for the Particle Swarm Algorithm (PS). At minimum the number of iterations (parameter `iterations`) and the number of particles (parameter `population_size`) have to be provided.

Usage

```

config_ps(
    iterations,
    population_size,
    iterations_same_cost = NULL,
    absolute_tol = NULL,
    alpha_vel = 0.5,
    alpha_evolution = 1,
    cognitive = 2,
    social = 2,
    inertia = 0.9
)

```

Arguments

<code>iterations</code>	maximum number of iterations.
<code>population_size</code>	number of particles.
<code>iterations_same_cost</code>	maximum number of consecutive iterations with the <i>same</i> (see the parameter <code>absolute_tol</code>) best cost before ending the minimization. If <code>NULL</code> the minimization continues for the number of iterations specified by the parameter <code>iterations</code> . Default is <code>NULL</code> .
<code>absolute_tol</code>	absolute tolerance when comparing best costs from consecutive iterations. If <code>NULL</code> the machine epsilon is used. Default is <code>NULL</code> .
<code>alpha_vel</code>	maximum velocity of particles, defined as a fraction of the range on each parameter. Default is <code>0.5</code> .
<code>alpha_evolution</code>	parameter to control the decreasing <code>alpha_vel</code> value with the iterations. Default is <code>1.0</code> (linear).
<code>cognitive</code>	parameter influencing the motion of the particle on the basis of distance between its current and best positions. Default is <code>2.0</code> .
<code>social</code>	parameter influencing the motion of the particle on the basis of distance between its current position and the best position in the swarm. Default is <code>2.0</code> .
<code>inertia</code>	parameter influencing the dependency of the velocity on its value at the previous iteration. Default <code>0.9</code> .

Value

`config_ps` returns an object of class `PSConfig`.

References

Eberhart R, Kennedy J (1995). "A new optimizer using particle swarm theory." In *MHS'95. Proceedings of the Sixth International Symposium on Micro Machine and Human Science*, 39–43. Ieee.

Examples

```
conf <- config_ps(iterations = 100, population_size = 50, iterations_same_cost = NULL,
  absolute_tol = NULL, alpha_vel = 0.5, alpha_evolution = 1.0, cognitive = 2.0,
  social = 2.0, inertia = 0.9)
```

config_sa

Configuration object for the Simulated Annealing Algorithm

Description

Create a configuration object for the Simulated Annealing algorithm (SA). At minimum the number of iterations (parameter `iterations`) and the number of particles (parameter `population_size`) have to be provided.

Usage

```
config_sa(
  iterations,
  population_size,
  iterations_same_cost = NULL,
  absolute_tol = NULL,
  T0 = 50,
  Ns = 3,
  Nt = 3,
  c_step = 2,
  Rt = 0.85,
  Wmin = 0.25,
  Wmax = 1.25
)
```

Arguments

<code>iterations</code>	maximum number of iterations.
<code>population_size</code>	number of particles.
<code>iterations_same_cost</code>	maximum number of consecutive iterations with the <i>same</i> (see the parameter <code>absolute_tol</code>) best cost before ending the minimization. If <code>NULL</code> the minimization continues for the number of iterations specified by the parameter <code>iterations</code> . Default is <code>NULL</code> .
<code>absolute_tol</code>	absolute tolerance when comparing best costs from consecutive iterations. If <code>NULL</code> the machine epsilon is used. Default is <code>NULL</code> .
<code>T0</code>	initial temperature. Default is 50.
<code>Ns</code>	number of iterations before changing velocity. Default is 3.

Nt	number of iterations before changing the temperature. Default is 3.
c_step	parameter involved in the velocity update. Default is 2.
Rt	scaling factor for the temperature. Default is 0.85.
Wmin	parameter involved in the generation of the starting point. Default is 0.25.
Wmax	parameter involved in the generation of the starting point. Default is 1.25.

Value

config_sa returns an object of class SAConfig.

References

Kirkpatrick S, Gelatt CD, Vecchi MP (1983). “Optimization by Simulated Annealing.” *Science*, **220**(4598), 671–680. doi:[10.1126/science.220.4598.671](https://doi.org/10.1126/science.220.4598.671).

Examples

```
conf <- config_sa(iterations = 100, population_size = 50, iterations_same_cost = NULL,
  absolute_tol = NULL, T0 = 50., Ns = 3., Nt = 3., c_step = 2., Rt = 0.85, Wmin = 0.25,
  Wmax = 1.25)
```

config_woa

Configuration object for the Whale Optimization Algorithm

Description

Create a configuration object for the Whale Optimization Algorithm (WOA). At minimum the number of iterations (parameter `iterations`) and the number of whales (parameter `population_size`) have to be provided.

Usage

```
config_woa(
  iterations,
  population_size,
  iterations_same_cost = NULL,
  absolute_tol = NULL
)
```

Arguments

`iterations` maximum number of iterations.
`population_size` number of whales.

iterations_same_cost	maximum number of consecutive iterations with the <i>same</i> (see the parameter <code>absolute_tol</code>) best cost before ending the minimization. If NULL the minimization continues for the number of iterations specified by the parameter <code>iterations</code> . Default is NULL.
absolute_tol	absolute tolerance when comparing best costs from consecutive iterations. If NULL the machine epsilon is used. Default is NULL.

Value

`config_woa` returns an object of class `WOAConfig`.

References

Mirjalili S, Lewis A (2016). “The Whale Optimization Algorithm.” *Advances in Engineering Software*, **95**, 51-67. ISSN 0965-9978, doi:10.1016/j.advengsoft.2016.01.008.

Examples

```
conf <- config_woa(iterations = 100, population_size = 50, iterations_same_cost = NULL,
absolute_tol = NULL)
```

`constrained_function` *Constrained function for minimization*

Description

Create a constrained function for minimization.

Usage

```
constrained_function(func, ...)
```

Arguments

<code>func</code>	original objective function.
<code>...</code>	one or more constraints of class <code>Constraint</code> . See constraint .

Value

`constrained_function` returns an object of class `ConstrainedFunction`.

constraint	<i>Constraint for minimization</i>
------------	------------------------------------

Description

Create a constraint function for constrained optimization. Only inequality constraints are supported.

Usage

```
constraint(func, inequality)
```

Arguments

func function describing the constraint.
inequality inequality type. Possible values: >, >=, <=, <.

Value

constraint returns an object of class Constraint.

Examples

```
g1 <- function(x) 0.0193*x[3] - (x[1]*0.0625)  
c1 <- constraint(g1, "<=")
```

freudenstein_roth_func	<i>Freudenstein Roth Function</i>
------------------------	-----------------------------------

Description

Implementation of 2-dimensional Freudenstein Roth function.

Usage

```
freudenstein_roth_func(x)
```

Arguments

x numeric or complex vector.

Details

On an 2-dimensional domain it is defined by

$$f(\vec{x}) = (x_1 - 13 + ((5 - x_2)x_2 - 2)x_2)^2 + (x_1 - 29 + ((x_2 + 1)x_2 - 14)x_2)^2$$

and is usually evaluated on $x_i \in [-10, 10]$, for all $i = 1, 2$. The function has one global minimum at $f(\vec{x}) = 0$ for $\vec{x} = [5, 4]$.

Value

The value of the function.

References

Rao S (2019). *Engineering optimization : theory and practice*. John Wiley and Sons, Ltd, Hoboken, NJ, USA. ISBN 978-1-119-45479-3.

G01InitPop	<i>Data set for example G01</i>
------------	---------------------------------

Description

This data set contains the initial positions for a population of size 20 to be used with the example G01.

get_population	<i>Get population positions</i>
----------------	---------------------------------

Description

Return a data.frame with the position of all individuals in the population at the specified iteration, from an object of class OptimizationResults produced with the option save_pop_history set to TRUE (see [MinimizerOpts](#)).

Usage

```
get_population(minimizer_result, iteration)
```

Arguments

minimizer_result an object of class OptimizationResults (see [OptimizationResults](#)).

iteration iteration number.

Value

An object of class data.frame.

griewank_func	<i>Griewank Function</i>
---------------	--------------------------

Description

Implementation of n-dimensional Griewank function.

Usage

`griewank_func(x)`

Arguments

`x` numeric or complex vector.

Details

On an n-dimensional domain it is defined by

$$f(\vec{x}) = 1 + \sum_{i=1}^n \frac{x_i^2}{4000} - \prod_{i=1}^n \cos\left(\frac{x_i}{\sqrt{i}}\right),$$

and is usually evaluated on $x_i \in [-600, 600]$, for all $i = 1, \dots, n$. The function has global minima at $f(\vec{x}) = 0$ for $x_i = 0$ for all $i = 1, \dots, n$.

Value

The value of the function.

References

Griewank AO (1981). "Generalized descent for global optimization." *Journal of optimization theory and applications*, **34**(1), 11–39.

list_of_algorithms	<i>Return the list of algorithms in EmiR</i>
--------------------	--

Description

Return a data.frame with the ID, description and configuration function name of all the algorithms implemented in EmiR.

Usage

`list_of_algorithms()`

Value

An object of class `data.frame`.

<code>list_of_functions</code>	<i>Return the list of pre-defined functions in EmiR</i>
--------------------------------	---

Description

Return a `data.frame` with function name, full name, and minimum and maximum number of parameters accepted for all the pre-defined functions in EmiR.

Usage

```
list_of_functions()
```

Value

An object of class `data.frame`.

<code>miele_cantrell_func</code>	<i>Miele Cantrell Function</i>
----------------------------------	--------------------------------

Description

Implementation of 4-dimensional Miele Cantrell Function.

Usage

```
miele_cantrell_func(x)
```

Arguments

`x` numeric or complex vector.

Details

On an 4-dimensional domain it is defined by

$$f(\vec{x}) = (e^{-x_1} - x_2)^4 + 100(x_2 - x_3)^6 + (\tan(x_3 - x_4))^4 + x_1^8$$

and is usually evaluated on $x_i \in [-2, 2]$, for all $i = 1, \dots, 4$. The function has one global minimum at $f(\vec{x}) = 0$ for $\vec{x} = [0, 1, 1, 1]$.

Value

The value of the function.

References

Cragg EE, Levy AV (1969). “Study on a supermemory gradient method for the minimization of functions.” *Journal of Optimization Theory and Applications*, **4**(3), 191–205.

minimize *Minimize an Objective Function*

Description

Minimize (or maximize) an objective function, possibly subjected to inequality constraints, using any of the algorithms available in EmiR.

Usage

```
minimize(algorithm_id, obj_func, parameters, config, constraints = NULL, ...)
```

Arguments

- | | |
|--------------|--|
| algorithm_id | id of the algorithm to be used. See list_of_algorithms for the list of the available algorithms. |
| obj_func | objective function be minimized/maximized. |
| parameters | list of parameters composing the search space for the objective function. Parameters are requested to be objects of class Parameter (see parameter). |
| config | an object with the configuration parameters of the chosen algorithm. For each algorithm there is different function for the tuning of its configuration parameter, as reported in the following list:

config_abc – configuration function for the <i>Artificial Bee Colony Algorithm</i> .
config_bat – configuration function for the <i>Bat Algorithm</i> .
config_cs – configuration function for the <i>Cuckoo Search Algorithm</i> .
config_ga – configuration function for the <i>Genetic Algorithm</i> .
config_gsa – configuration function for the <i>Gravitational Search Algorithm</i> .
config_gwo – configuration function for the <i>Grey Wolf Optimizer Algorithm</i> .
config_hs – configuration function for the <i>Harmony Search Algorithm</i> .
config_ibs – configuration function for the <i>Improved Harmony Search Algorithm</i> .
config_mfo – configuration function for the <i>Moth-flame Optimization Algorithm</i> .
config_ps – configuration function for the <i>Particle Swarm Algorithm</i> .
config_sa – configuration function for the <i>Simulated Annealing algorithm</i> .
config_woa – configuration function for the <i>Whale Optimization Algorithm</i> . |
| constraints | list of constraints. Constraints are requested to be objects of class Constraint (see constraint). |
| ... | additional options (see MinimizerOpts). |

Value

minimize returns an object of class OptimizationResults (see [OptimizationResults](#)).

Examples

```
## Not run:
results <- minimize(algorithm_id = "BAT", obj_func = ob, config = conf,
  parameters = list(p1,p2, p3, p4), constraints = list(c1,c2,c3),
  save_pop_history = TRUE, constrained_method = "BARRIER",
  constr_init_pop = TRUE, oob_solutions = "RBC", seed = 1)

## End(Not run)
```

MinimizerOpts

EmiR optimization options

Description

A S4 class storing the options for the optimization algorithms in EmiR.

Slots

maximize if TRUE the objective function is maximized instead of being minimized. Default is FALSE.

silent_mode if TRUE no output to console is generated. Default is FALSE.

save_pop_history if TRUE the position of all individuals in the population at each iteration is stored. This is necessary for functions like plot_population and animate_population to work. Default is FALSE.

constrained_method method for constrained optimization. Possible values are:

- "PENALTY" - Penalty Method: the constrained problem is converted to an unconstrained one, by adding a *penalty function* to the objective function. The penalty function consists of a *penalty parameter* multiplied by a measure of violation of the constraints. The penalty parameter is multiplied by a scale factor (see penalty_scale) at every iteration;
- "BARRIER" - Barrier Method: the value of the objective function is set equal to an arbitrary large positive (or negative in case of maximization) number if any of the constraints is violated;
- "ACCREJ" - Acceptance-Rejection method: a solution violating any of the constraints is replaced by a randomly generated new one in the feasible region. Default is "PENALTY".

penalty_scale scale factor for the *penalty parameter* at each iteration. It should be greater than 1. Default is 10.

start_penalty_param initial value of the *penalty parameter*. It should be greater than 0. Default is 2.

`max_penalty_param` maximum value for the *penalty parameter*. It should be greater than 0. Default is 1.e+10.

`constr_init_pop` if TRUE the initial population is generated in the *feasible region* only. Default is TRUE.

`oob_solutions` strategy to treat out-of-bound solutions. Possible values are:

- "RBC" - Reflective Boundary Condition: the solution is placed back inside the search domain at a position which is distanced from the boundary as the out-of-bound excess. Depending on the optimization algorithm, the velocity of the corresponding individual of the population could be also inverted;
- "PBC" - Periodic Boundary Condition: the solution is placed back inside the search domain at a position which is distanced from the *opposite* boundary as the out-of-bound excess;
- "BAB" - Back At Boundary: the solution is placed back at the boundaries for the out-of-bound dimensions;
- "DIS" - Disregard the solution: the solution is replaced by a new one, which is randomly generated in the search space. Default is "DIS".

`seed` seed for the internal random number generator. Accepted values are strictly positive integers. If NULL a random seed at each execution is used. Default is NULL.

`initial_population` manually specify the position of the initial population. A $n \times d$ matrix has to be provided, where n is the population size and d is the number of parameters the objective function is minimized with respect to.

`generation_function` manually specify the function to generate to new solutions.

OptimizationResults *EmiR optimization results*

Description

A S4 class storing all relevant data from an optimization with EmiR.

Slots

`algorithm` the name of the algorithm.

`iterations` the number of iterations.

`population_size` the number of individuals in the population.

`obj_function` the minimized/maximized objective function.

`constraints` the constraints the objective function is subjected to.

`best_cost` the best value of the objective function found.

`best_parameters` the parameter values for which the best cost was obtained.

`parameter_range` the range on the parameters.

`pop_history` list containing the positions of all individuals in the population at each iteration. The list is filled only if `save_pop_history` is TRUE in the options of the minimizer (see [Minimize-rOpts](#)).

`cost_history` the vector storing the best value of the objective function at each iteration.
`exec_time_sec` the execution time in seconds.
`is_maximization` if TRUE the objective function has been maximized instead of being minimized.

parameter	<i>Parameter for minimization</i>
-----------	-----------------------------------

Description

Create a parameter the objective function is minimized with respect to.

Usage

```
parameter(name, min_val, max_val, integer = FALSE)
```

Arguments

<code>name</code>	name of the parameter.
<code>min_val</code>	minimum value the parameter is allowed to assume during minimization.
<code>max_val</code>	maximum value the parameter is allowed to assume during minimization.
<code>integer</code>	if TRUE the parameter is constrained to be integer. Default is FALSE.

Value

`parameter` returns an object of class `Parameter`.

Examples

```
p1 <- parameter("x1", 18, 32, integer = TRUE)
```

parameters	<i>Set of parameters for minimization</i>
------------	---

Description

Create the set of parameters the objective function is minimized with respect to. A $2 \times n$ matrix or a $3 \times n$ matrix, where the first row is for the lower limits, the second one is for the upper limits, and the (optional) third one is to specify if a parameter is constrained to be integer. In case the third row is not provided, all the parameters are treated as continuous. The name of each of the n parameters is automatically generated and it is of the form x_i , where $i = 1, \dots, n$.

Usage

```
parameters(values)
```

Arguments

values a $2 \times n$ matrix or a $3 \times n$ matrix.

Value

parameters returns a list of objects of class Parameter.

plot_history	<i>Plot minimization history</i>
--------------	----------------------------------

Description

Plot the minimization history as a function of the number of iterations.

Usage

```
plot_history(minimizer_result, ...)
```

Arguments

minimizer_result an object of class OptimizationResults (see [OptimizationResults](#)).

... additional arguments, such as graphical parameters (see [plot](#)).

plot_population	<i>Plot the population position</i>
-----------------	-------------------------------------

Description

Plot the position of all individuals in the population, at a given iteration, for 1D and 2D functions. The plot can be produced only if save_pop_history is TRUE in the options of the minimizer (see [MinimizerOpts](#)).

Usage

```
plot_population(minimizer_result, iteration, n_points = 100)
```

Arguments

minimizer_result an object of class OptimizationResults (see [OptimizationResults](#)).

iteration iteration at which the population is plotted.

n_points number of points per dimension used to draw the objective function. Default is 100.

rastrigin_func *Rastrigin Function*

Description

Implementation of n-dimensional Rastrigin function.

Usage

rastrigin_func(x)

Arguments

x numeric or complex vector.

Details

On an n-dimensional domain it is defined by:

$$f(\vec{x}) = 20n + \sum_{i=1}^n (x_i^2 - 20 \cos(2\pi x_i)),$$

and is usually evaluated on $x_i \in [-5.12, 5.12]$, for all $i = 1, \dots, n$. The function has one global minimum at $f(\vec{x}) = 0$ for $x_i = 0$ for all $i = 1, \dots, n$.

Value

The value of the function.

References

Rastrigin LA (1974). "Systems of extremal control." *Nauka*.

rosenbrock_func *Rosenbrock Function*

Description

Implementation of n-dimensional Rosenbrock function, with $n \geq 2$.

Usage

rosenbrock_func(x)

Arguments

x numeric or complex vector.

Details

On an n-dimensional domain it is defined by

$$f(\vec{x}) = \sum_{i=1}^{n-1} [100(x_{i+1} - x_i^2)^2 + (x_i - 1)^2],$$

and is usually evaluated on $x_i \in [-5, 10]$, for all $i = 1, \dots, n$. The function has one global minimum at $f(\vec{x}) = 0$ for $x_i = 1$ for all $i = 1, \dots, n$.

Value

The value of the function.

References

Rosenbrock HH (1960). “An Automatic Method for Finding the Greatest or Least Value of a Function.” *The Computer Journal*, 3(3), 175–184. doi:10.1093/comjnl/3.3.175.

 schwefel_func

Schwefel Function

Description

Implementation of n-dimensional Schwefel function.

Usage

schwefel_func(x)

Arguments

x numeric or complex vector.

Details

On an n-dimensional domain it is defined by

$$f(\vec{x}) = \sum_{i=1}^n [-x_i \sin(\sqrt{|x_i|})],$$

and is usually evaluated on $x_i \in [-500, 500]$, for all $i = 1, \dots, n$. The function has one global minimum at $f(\vec{x}) = -418.9829n$ for $x_i = 420.9687$ for all $i = 1, \dots, n$.

Value

The value of the function.

References

Schwefel H (1981). *Numerical optimization of computer models*. John Wiley & Sons, Inc.

styblinski_tang_func *Styblinski-Tang Function*

Description

Implementation of n-dimensional Styblinski-Tang function.

Usage

styblinski_tang_func(x)

Arguments

x numeric or complex vector.

Details

On an n-dimensional domain it is defined by

$$f(\vec{x}) = \frac{1}{2} \sum_{i=1}^n (x_i^4 - 16x_i^2 + 5x_i),$$

and is usually evaluated on $x_i \in [-5, 5]$, for all $i = 1, \dots, n$. The function has one global minimum at $f(\vec{x}) = -39.16599n$ for $x_i = -2.903534$ for all $i = 1, \dots, n$.

Value

The value of the function.

References

Styblinski MA, Tang T (1990). "Experiments in nonconvex optimization: Stochastic approximation with function smoothing and simulated annealing." *Neural Networks*, **3**(4), 467–483. doi:10.1016/08936080(90)90029k.

Index

* data

G01InitPop, [22](#)

ackley_func, [3](#)
animate_population, [3](#)

bohachevsky_func, [4](#)

config_abc, [5](#), [25](#)
config_algo, [6](#)
config_bat, [7](#), [25](#)
config_cs, [8](#), [25](#)
config_ga, [9](#), [25](#)
config_gsa, [11](#), [25](#)
config_gwo, [12](#), [25](#)
config_hs, [13](#), [25](#)
config_ihs, [14](#), [25](#)
config_mfo, [15](#), [25](#)
config_ps, [16](#), [25](#)
config_sa, [18](#), [25](#)
config_woa, [19](#), [25](#)
constrained_function, [20](#)
constraint, [20](#), [21](#), [25](#)

freudenstein_roth_func, [21](#)

G01InitPop, [22](#)
get_population, [22](#)
griewank_func, [23](#)

list_of_algorithms, [6](#), [23](#), [25](#)
list_of_functions, [24](#)

miele_cantrell_func, [24](#)
minimize, [25](#)
MinimizerOpts, [3](#), [22](#), [25](#), [26](#), [27](#), [29](#)

OptimizationResults, [4](#), [22](#), [26](#), [27](#), [29](#)

parameter, [25](#), [28](#)
parameters, [28](#)

plot, [29](#)
plot_history, [29](#)
plot_population, [29](#)

rastrigin_func, [30](#)
rosenbrock_func, [30](#)

schwefel_func, [31](#)
styblinski_tang_func, [32](#)